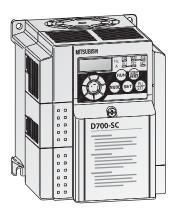
The FR-D700 SC Series



The FR-D700 SC is a pace-setter in the miniature drive system class. It features ultra-compact dimensions, simple and secure operation and a wide range of technology functions. The integrated digital dial gives the user fast, direct access to all important drive parameters.

Output range:

FR-D720S SC: 0.1–2.2 kW, 200–240 V AC, single-phase FR-D740 SC: 0.4–7.5 kW, 380–480 V AC, three-phase

Available accessories:

Optional control units, versatile options and useful accessories are available for this frequency inverter.

Please refer to page 38 for details.

Technical Details FR-D700 SC

Product line			FR-D720S-□-SC-EC/-E6						FR-D74	FR-D740SC-EC/-E6						
			008	014	025	042	070	100	012	022	036	050	080	120	160	
	Rated motor capacity ©	kW	0.1	0.2	0.4	0.75	1.5	2.2	0.4 (0.55)	0.75 (1.1)	1.5 (2.2)	2.2 (3)	3.7 (4)	5.5 (7.5)	7.5 (11)	
Output	Rated output kVA		0.3	0.5	1.0	1.6	2.8	3.8	1.2	2.0	3.0	4.6	7.2	9.1	13.0	
	Rated current [®]	0.8	1.4	2.5	4.2	7.0	10.0	1.2 (1.4)	2.2 (2.6)	3.6 (4.3)	5.0 (6.0)	8.0 (9.6)	12.0 (14.4)	16.0 (19.2)		
	Overload capacity (4)	150 % of rated motor capacity for 60 s; 200 % for 0.5 s														
	Voltage ®		3-phase AC, 0 V to power supply voltage													
Input	Power supply voltage	1-phase, 200–240 V AC, -15 %/+10 %							3-phase, 380-480 V AC, -15 %/+10 %							
	Voltage range	170–264 V AC at 50/60 Hz 325–528 V AC at 50/60 Hz														
	Power supply frequency		50/60 Hz ± 5 %													
	Rated input capacity ® k		0.5	0.9	1.5	2.3	4.0	5.2	1.5	2.5	4.5	5.5	9.5	12	17	
Control	Control method		V/f control, optimum excitation control or general-purpose magnetic flux vector control													
	Modulation control		Sine evaluated PWM, Soft PWM													
	PWM switching freque	0.7–14.5 kHz, user adjustable														
	Frequency range Hz		0.2–400													
	Frequency resolution	Analog	0.06 Hz/0–50 Hz (terminal 2, 4: 0–10 V/10 Bit) 0.12 Hz/0–50 Hz (terminal 2, 4: 0–5 V/9 Bit 0.06 Hz/0–50 Hz (terminal 4: 0–20 mA/10 Bit)													
		Digital	0.01 Hz	!												
	Frequency precision	$\pm 1\%$ of max. output frequency (temperature range 25 °C \pm 10 °C) during analog input; $\pm 0.01\%$ of max. output frequency during digital input (set via Digital Dial)														
	Voltage/frequency char	Base frequency adjustable from 0 to 400 Hz Constant torque/variable torque pattern can be selected														
	Possible starting torque	≥150 %/1 Hz (for vector control oder slip compensation)														
	Torque boost	Manual torque boost														
	Acceleration/decelerati	0.1 to 3600 s (may be set individually for acceleration and deceleration)														
	Acceleration/decelerati	Linear or S-pattern acceleration/deceleration mode selectable														
	Braking torque DC braking		Operating frequency: 0–120 Hz, operating time: 0–10 s, voltage: 0–30 % (externally adjustable)													
	Current stall prevention operation level		Operat	ion current	level setting	g 0–200 %,	user adjust	able								
	Motor protection		Electronic motor protection relay (rated current user adjustable)													

Remarks:

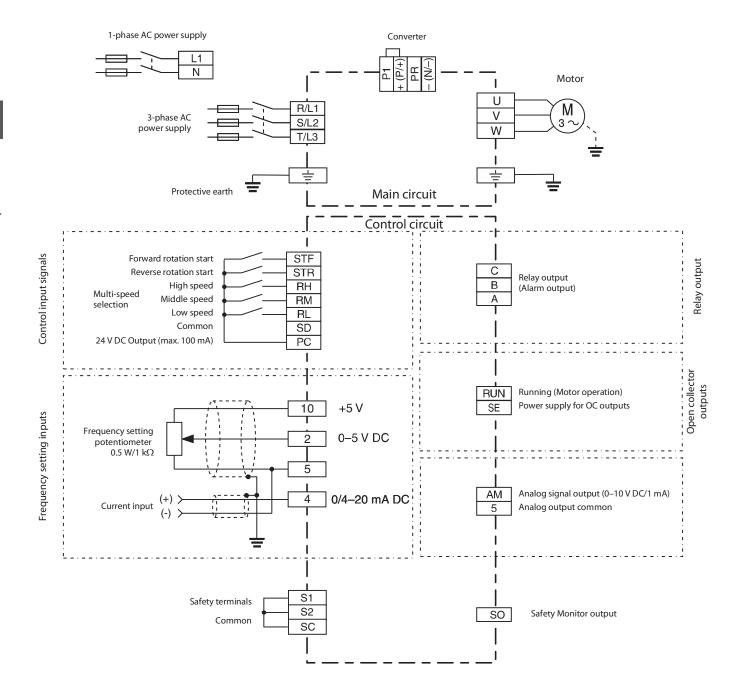
Explanation for ① to ⑥ see next page.

Broduct line			FR-D720S-□-SC-EC/-E6						FR-D740	FR-D740SC-EC/-E6						
Product line		008	014	025	042	070	100	012	022	036	050	080	120	160		
	Frequency setting	Analog input		2: 0–5 V DC 4: 0–5 V DC		., 0/4–20 m	A									
Control	signal	Digital input	Entered from operation panel or parameter unit. Frequency setting increment is selectable.													
signals for operation	Operation functions		Maximum/minimum frequency setting, frequency jump operation, external thermal relay input selection, automatic restart after instantaneous power failure operation, forward/reverse rotation prevention, remote setting, second function, multi-speed operation, regeneration avoidance, slip compensation operation mode selection, offline auto tuning function, PID control, computer link operation (RS485), optimum excitation control, power failure stop, speed smoothing control, Modbus-RTU													
Control	Input signals		Any of 5 signals can be selected using parameters 178 to 182 (input terminal function selection): multi-speed selection, remote setting, second function selection, terminal 4 input selection, JOG operation selection, PID control valid terminal, external thermal input, PU-external operation switchover, V/F switchover, output stop, start self-holding selection, traverse function selection, forward rotation, reverse rotation command, inverter reset, PU-NET operation switchover, external-NET operation switchover, command source switchover, inverter operation enable signal, and PU operation external interlock													
signals for operation	Output signals	Operating status	Can be selected using parameters 190 and 192 (output terminal function selection): inverter operation, up-to-frequency, overload alarm, output frequency detection, regenerative brake prealarm, electronic thermal relay function prealarm, inverter operation ready, output current detection, zero current detection, PID lower limit, PID upper limit, PID forward/reverse rotation output, fan alarm , heatsink overheat pre-alarm, deceleration at an instantaneous power failure, PID control activated, safety monitor output, safety monitor output 2, during retry, life alarm, fault output current average value monitor, maintenance timer alarm, remote output, alarm output, fault output													
		Analog signal	0-10 V D	C												
	Displays on operation panel or parameter unit	Operating status	Output frequency, motor current (steady), output voltage, frequency setting, cumulative energization time, actual operation time, converter output voltage, regenerative brake duty, electronic thermal relay function load factor, output current peak value, converter output voltage pea value, motor load factor, PID set point, PID measured value, PID deviation, inverter I/O terminal monitor, output power, cumulative power, mo thermal load factor, inverter thermal load factor, PTC thermistor resistance.								age peak					
Display option	(FR-PU07)	Alarm display	Fault definition is displayed when the fault occurs and the past 8 fault definitions (output voltage/current/frequency/cumulative energization time right before the fault occurs) are stored.													
	Additional displays on parameter unit FR-PU07	Operating status	Not used													
		Interactive guidance	Interactive guide for operation and troubleshooting via help function													
Protection	Functions	Overcurrent during acceleration, overcurrent during constant speed, overcurrent during deceleration, overvoltage during acceleration, overvoltage during constant speed, overvoltage during deceleration, inverter protection thermal operation, motor protection thermal operation, heatsink overheat, input phase failure , output side earth (ground) fault overcurrent at start , output phase failure, external thermal relay operation, PTC thermistor operation , parameter error, PU disconnection, retry count excess. PU fault, brake transistor alarm, inrush resistance overheat analog input error, stall prevention operation, output current detection value exceeded, safety circuit fault, Fan alarm, overcurrent stall prevention, overvoltage stall prevention, PU stop, parameter write error, regenerative brake prealarm, electronic thermal relay function prealarm, maint nance output, undervoltage, operation panel lock, password locked, inverter reset, safety torque off														
	Protective structure		IP20			·					·					
	Cooling	Self-cooling Fan cooling					Self-cooling Fan cooling									
	Power loss W		14	20	32	50	80	110	40	55	90	100	180	240	280	
Others	Weight	kg	0.5	0.6	0.9	1.1	1.5	1.9	1.2	1.2	1.3	1.4	1.5	3.1	3.1	
	Dimensions mm (WxHxD)		68x128x80.5 68x128 68x128 x162.5 x165.5 x165							c155						
Ordor in																
Order in-	Single painted PCB(EC)	Art. no.	247595	247596	247597	247598	247599	247600	247601	247602	247603	247604	247605	247606	247607	

Remarks:

- ① The applied motor capacity indicated is the maximum capacity applicable for use of the Mitsubishi Electric 4-pole standard motor. The motor capacity ratings in brackets are for ambient temperatures up to 40 °C.
- $\ \ \, \ \ \,$ The specifications of the rated output capacity are related to a motor voltage of 440 V.
- $\ensuremath{\ensuremath{\Im}}$ The rated output current in brackets are for ambient temperatures up to 40 °C.
- The % value of the overload capacity indicated is the ratio of the overload current to the inverter's rated output current. For repeated duty, allow time for the inverter and motor to return to or below the temperatures under 100 % load.
- ⑤ The maximum output voltage does not exceed the power supply voltage. The maximum output voltage can be changed within the setting range. However, the pulse voltage value of the inverter output side voltage remains unchanged at about √2 that of the power supply.
- (including those of the input reactor and cables).
- ${ \ensuremath{ \bigcirc \hspace{-8.7pt} }} \ \ {\rm FR-D720S-070SC} \ {\rm or} \ {\rm above}, \ {\rm FR-D740-036SC} \ {\rm or} \ {\rm above}$
- ® This protective function is available with the three-phase power input specification model only.
- This protective function does not function in the initial status.
 For overseas types refer to page 78.

Block Diagram FR-D700 SC



Assignment of Signal Terminals

Control connection STR Reverse rotation start The motor rotates forward, if a signal is applied to terminal STF. If the signals STF and STR are applied simultaneous the STOP command is given. The motor rotates reverse, if a signal is applied to terminal STR. If the signals STF and STR are applied simultaneous the STOP command is given. RH, RM, RL Multi-speed selection Preset of 15 different output frequencies; programmable. A determined control function is activated, if the corresponding terminal is connected to the terminal SD (sink low The SD terminal is isolated from the digital circuits via optocouplers. When connecting the transistor output (open collector output), such as a programmable controller (PLC), connected to the terminal power supply for transistor output to this terminal to prevent a malfunction caused by undesirable curre logic has been selected, connect this terminal with 0 V of the external power supply.	gic).
The motor rotates reverse, if a signal is applied to terminal STR. If the signals STF and STR are applied simultaneo the STOP command is given. RH, RM, RL Multi-speed selection Preset of 15 different output frequencies; programmable. A determined control function is activated, if the corresponding terminal is connected to the terminal SD (sink lot The SD terminal is isolated from the digital circuits via optocouplers. When connecting the transistor output (open collector output), such as a programmable controller (PLC), connecting the transistor output to this terminal to prevent a malfunction caused by undesirable curre	gic).
A determined control function is activated, if the corresponding terminal is connected to the terminal SD (sink lost The SD terminal is isolated from the digital circuits via optocouplers. When connecting the transistor output (open collector output), such as a programmable controller (PLC), connecting the transistor output to this terminal to prevent a malfunction caused by undesirable curre	<i>,</i>
Contact input common (sink) 24 V DC power supply common 2 V DC power supply	,
ingle has been selected, connect this terminal with a viville external power supply.	
PC Contact input common (source) 24 V DC/0.1 A output In sink logic, when activated by open collector transistors (e.g. PLC) the positive pole of an external power supply connected to the PC terminal. In source logic, the PC terminal serves as common reference point for the control in	
10 Voltage output for potentiometer Output voltage 5 V DC. Max. output current 10 mA Recommended potentiometer: 1 kΩ, 0.5 W linear (multi-turn potentiometer)	
Input for frequency Setting value $0-5$ (10) V is applied to this terminal. The voltage range is preset to $0-5$ V. The input resistance is $10 \text{ k}\Omega \pm 1\text{k}\Omega$. The maximum permitted voltage is 20 V DC.	
Setting value specification Terminal 5 is the reference point for all analog setting values and for the analog output signal AM. The terminal is isolated from the reference potential of the control circuit and should not be earthed for reasons of noise in the terminal is isolated from the reference potential of the control circuit and should not be earthed for reasons of noise in the terminal is isolated from the reference potential of the control circuit and should not be earthed for reasons of noise in the terminal is isolated from the reference potential of the control circuit and should not be earthed for reasons of noise in the terminal is isolated from the reference potential of the control circuit and should not be earthed for reasons of noise in the terminal is isolated from the reference potential of the control circuit and should not be earthed for reasons of noise in the terminal is isolated from the reference potential of the control circuit and should not be earthed for reasons of noise in the terminal is isolated from the reference potential of the control circuit and should not be earthed for reasons of noise in the terminal is isolated from the reference potential of the control circuit and should not be earthed for reasons of noise in the terminal is isolated from the reference potential of the control circuit and should not be earthed for the control circuit and should not be earthed for the control circuit and should not be earthed for the control circuit and should not be earthed for the control circuit and should not be earthed for the control circuit and should not be earthed for the control circuit and should not be earthed for the control circuit and should not be earthed for the control circuit and should not be earthed for the control circuit and should not be earthed for the control circuit and should not be earthed for the control circuit and should not be earthed for the control circuit and should not be earthed for the control circuit and should not be earthed for the control cir	immunity.
Inputting 4–20 mA DC (or 0–5 V, 0–10 V) provides the maximum output frequency at 20 mA and makes input at tional. This input signal is valid only when the AU signal is on (terminal 2 input is invalid). Use Pr. 267 to switch fixed to 20 mA (initial setting), 0–5 V DC and 0–10 V DC. Set the voltage/current input switch in the "V" position to select voltage input (0–5 V/0–10 V).	
A, B, C Relay output (alarm output) The alarm is output via relay contacts (C-B = Normally Open, C-A = Normally Closed). The maximum contact load is 230 V AC/0.3 A or 30 V DC/0.3 A.	
Switched low (voltage of terminal SE is output) when the inverter output frequency is equal to or higher than the (initial value 0.5 Hz). Switched high during stop or DC injection brake operation. (Low indicates that the open col transistor is on (conducts). High indicates that the transistor is off (does not conduct).) Signal Signal Switched low (voltage of terminal SE is output) when the inverter output frequency is equal to or higher than the (initial value 0.5 Hz). Switched high during stop or DC injection brake operation. (Low indicates that the open col transistor is off (does not conduct).) Permissible load 24 V DC (maximum 27 V DC)/0.1 A (a voltage drop is 3.4 V maximum when the signal is on).	
Outputs SE Reference potential for signal noutputs Reference potential for the signal RUN. This terminal is isolated from the reference potential of the control circuit 5 and SD.	
Select one e.g. output frequency from monitor items. Not output during inverter reset. The output signal is proportion the magnitude of the corresponding monitoring item. Output item (initial setting): Output frequency Output signal 0—10 V DC. Permissible load current 1 mA (load impedance 10 kW or more), resolution 8 bit	ortional to
Interface — PU connector (RS485) Communications via RS485	
S1, S2 Safety inputs	
Safety connection SC Reference potential for safety inputs When the safety functions are not used, the existing jumpers between the terminals S1-SC and S2-SC must not be otherwise an operation of the frequency inverter is not possible.	e removed,
SO Safety monitor output	

Assignment of Main Circuit Terminals

Function	Terminal	Designation	Description						
	L1, N	Power supply 1-phase	Connect to the commercial power supply.						
	R/L1, S/L2, T/L3 Power supply 3-phase		Keep these terminals open when using the harmonic converter (FR-HC) or power regeneration common converter (FR-CV).						
	+ (P/+), - (N/-)	External brake unit connection	Connect the brake unit (FR-BU2), power regeneration common converter (FR-CV) or the Harmonic Converter (FR-HC) to the terminals $+$ (P/+) and $-$ (N/ $-$).						
Main circuit connection	+ (P/+), P1	DC reactor connection	An optional DC reactor can be connected to the terminals P1 and $+$ (P/ $+$). Before connecting the DC reactor, disconnect the jumper from terminals P1 and $+$ (P/ $+$).						
	+ (P/+), PR	External brake resistor connection	Connect a brake transistor (FR-ABR, MRS) across terminals $+$ (P/+) and PR. (The brake resistor can not be connected to the FR-D720S-008 and 014.)						
	U, V, W	Motor connection	Voltage output of the inverter (3-phase, 0 V up to input voltage, 0.2—400 Hz)						
	Ť	PE	Protective earth connection of inverter						